



# VN920SP-E

## HIGH SIDE DRIVER

**Table 1. General Features**

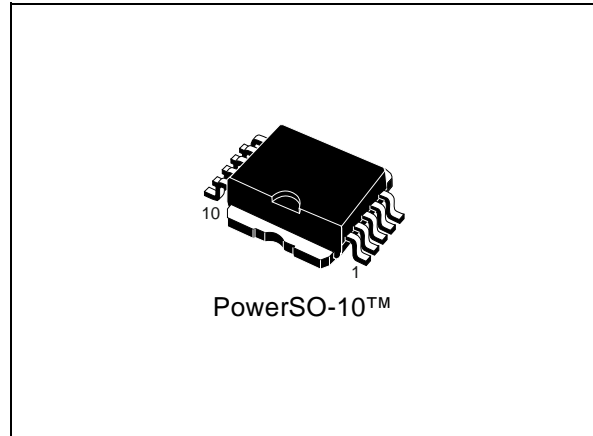
Type	R <sub>DS(on)</sub>	I <sub>OUT</sub>	V <sub>CC</sub>
VN920SP-E	15mΩ	30 A	36 V

- CMOS COMPATIBLE INPUT
- PROPORTIONAL LOAD CURRENT SENSE
- SHORTED LOAD PROTECTION
- UNDERVOLTAGE AND OVERVOLTAGE SHUTDOWN
- OVERVOLTAGE CLAMP
- THERMAL SHUTDOWN
- CURRENT LIMITATION
- PROTECTION AGAINST LOSS OF GROUND AND LOSS V<sub>CC</sub>
- VERY LOW STAND-BY POWER DISSIPATION
- REVERSE BATTERY PROTECTION (\*)
- IN COMPLIANCE WITH THE 2002/95/EC EUROPEAN DIRECTIVE

### DESCRIPTION

The VN920SP-E is a monolithic device designed in STMicroelectronics VIPower M0-3 Technology, intended for driving any kind of load with one side connected to ground. Active V<sub>CC</sub> pin voltage clamp protects the device against low energy spikes (see ISO7637 transient compatibility table).

**Figure 1. Package**



Active current limitation combined with thermal shutdown and automatic restart protect the device against overload. The device integrates an analog current sense output which delivers a current proportional to the load current. Device automatically turns off in case of ground pin disconnection.

**Table 2. Order Codes**

Package	Tube	Tape and Reel
PowerSO-10™	VN920SP-E	VN920SPTR-E

Note: (\*) See application schematic at page 9.



Figure 3. Configuration Diagram (Top View) &amp; Suggested Connections for Unused and N.C. Pins

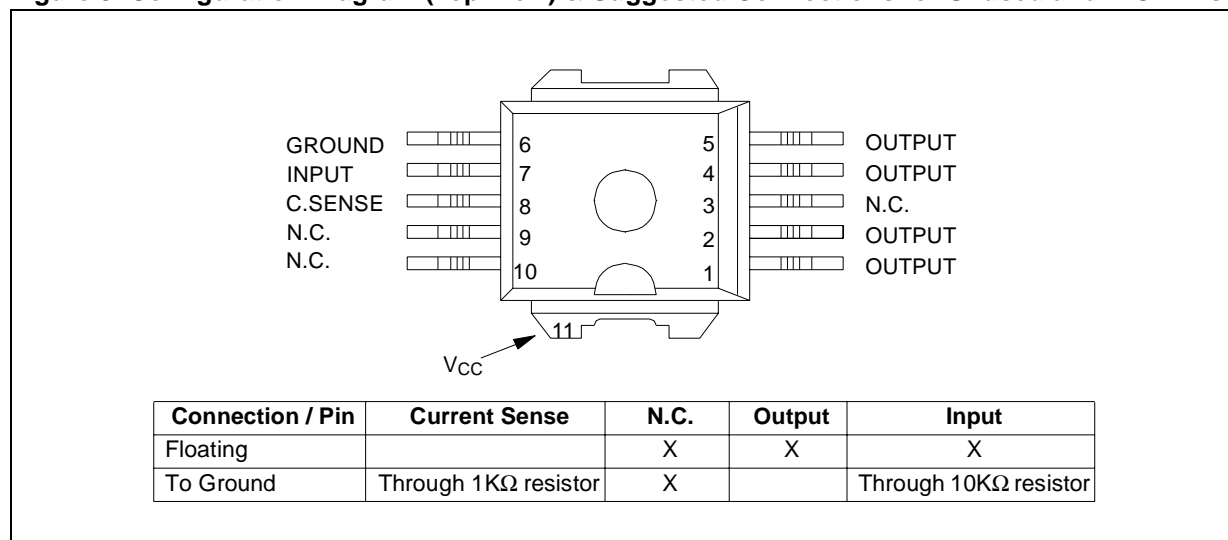


Figure 4. Current and Voltage Conventions

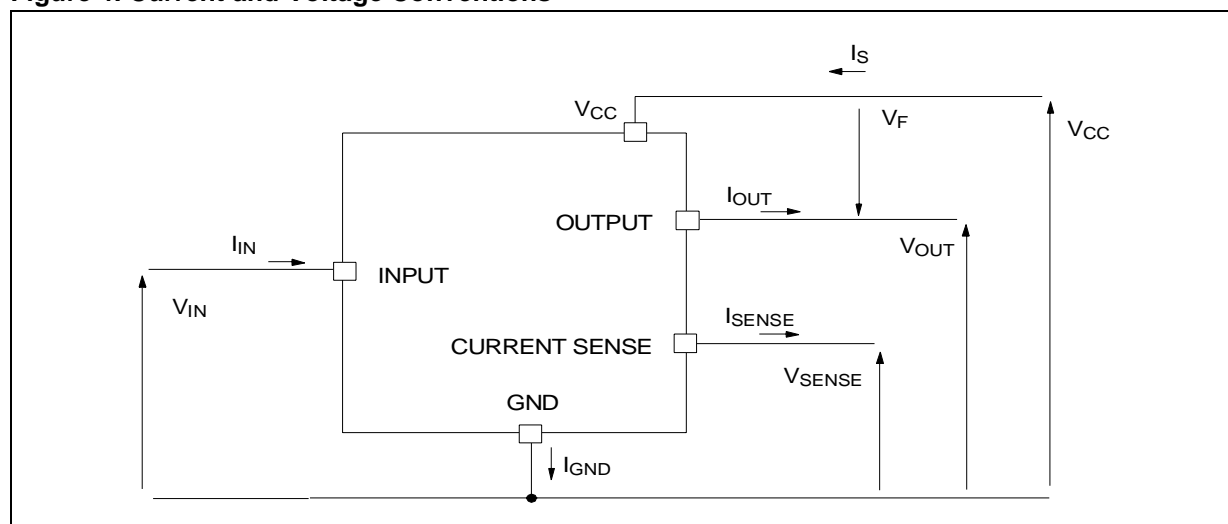


Table 4. Thermal Data

Symbol	Parameter		Value		Unit
$R_{thj-case}$	Thermal Resistance Junction-case	Max	1.3		$^{\circ}\text{C}/\text{W}$
$R_{thj-amb}$	Thermal Resistance Junction-ambient	Max	51.3 <sup>(1)</sup>	37 <sup>(2)</sup>	$^{\circ}\text{C}/\text{W}$

<sup>(1)</sup> When mounted on a standard single-sided FR-4 board with 0.5cm<sup>2</sup> of Cu (at least 35 $\mu\text{m}$  thick).

<sup>(2)</sup> When mounted on a standard single-sided FR-4 board with 6 cm<sup>2</sup> of Cu (at least 35 $\mu\text{m}$  thick).

**ELECTRICAL CHARACTERISTICS** ( $8V < V_{CC} < 36V$ ;  $-40^{\circ}C < T_j < 150^{\circ}C$  unless otherwise specified)

**Table 5. Power**

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
$V_{CC}$	Operating Supply Voltage		5.5	13	36	V
$V_{USD}$	Undervoltage Shut-down		3	4	5.5	V
$V_{OV}$	Overvoltage Shut-down		36			V
$R_{ON}$	On State Resistance	$I_{OUT}=10A$ ; $T_j = 25^{\circ}C$			15	$m\Omega$
		$I_{OUT}=10A$			30	$m\Omega$
		$I_{OUT}=3A$ ; $V_{CC}=6V$			50	$m\Omega$
$V_{clamp}$	Clamp Voltage	$I_{CC}=20mA$ (See note 1)	41	48	55	V
$I_S$	Supply Current	Off State; $V_{CC}=13V$ ; $V_{IN}=V_{OUT}=0V$		10	25	$\mu A$
		Off State; $V_{CC}=13V$ ; $T_j=25^{\circ}C$ ; $V_{IN}=V_{OUT}=0V$		10	20	$\mu A$
		On State; $V_{CC}=13V$ ; $V_{IN}=5V$ ; $I_{OUT}=0$ ; $R_{SENSE}=3.9K\Omega$			5	$mA$
$I_{L(off1)}$	Off State Output Current	$V_{IN}=V_{OUT}=0V$	0		50	$\mu A$
$I_{L(off2)}$	Off State Output Current	$V_{IN}=0V$ ; $V_{OUT}=3.5V$	-75		0	$\mu A$
$I_{L(off3)}$	Off State Output Current	$V_{IN}=V_{OUT}=0V$ ; $V_{CC}=13V$ ; $T_j = 125^{\circ}C$			5	$\mu A$
$I_{L(off4)}$	Off State Output Current	$V_{IN}=V_{OUT}=0V$ ; $V_{CC}=13V$ ; $T_j = 25^{\circ}C$			3	$\mu A$

Note: 1.  $V_{clamp}$  and  $V_{OV}$  are correlated. Typical difference is 5V.

**Table 6. Switching** ( $V_{CC} = 13V$ )

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
$t_{d(on)}$	Turn-on Delay Time	$R_L=1.3\Omega$ (see figure 2)		50		$\mu s$
$t_{d(off)}$	Turn-off Delay Time	$R_L=1.3\Omega$ (see figure 2)		50		$\mu s$
$\frac{dV_{OUT}}{dt_{(on)}}$	Turn-on Voltage Slope	$R_L=1.3\Omega$ (see figure 2)		See relative diagram		$V/\mu s$
$\frac{dV_{OUT}}{dt_{(off)}}$	Turn-off Voltage Slope	$R_L=1.3\Omega$ (see figure 2)		See relative diagram		$V/\mu s$

**Table 7. Logic Input**

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
$V_{IL}$	Input Low Level				1.25	V
$I_{IL}$	Low Level Input Current	$V_{IN}=1.25V$	1			$\mu A$
$V_{IH}$	Input High Level		3.25			V
$I_{IH}$	High Level Input Current	$V_{IN}=3.25V$			10	$\mu A$
$V_{I(hyst)}$	Input Hysteresis Voltage		0.5			V
$V_{ICL}$	Input Clamp Voltage	$I_{IN}=1mA$	6	6.8	8	V
		$I_{IN}=-1mA$		-0.7		V

## ELECTRICAL CHARACTERISTICS (continued)

Table 8. V<sub>CC</sub> - Output Diode

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V <sub>F</sub>	Forward on Voltage	-I <sub>OUT</sub> =5.3A; T <sub>J</sub> =150°C			0.6	V

Table 9. Protections (see note 2)

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
T <sub>TSD</sub>	Shut-down Temperature		150	175	200	°C
T <sub>R</sub>	Reset Temperature		135			°C
T <sub>hyst</sub>	Thermal Hysteresis		7	15		°C
I <sub>lim</sub>	DC Short Circuit Current	V <sub>CC</sub> =13V 5V<V <sub>CC</sub> <36V	30	45	75 75	A A
V <sub>demag</sub>	Turn-off Output Clamp Voltage	I <sub>OUT</sub> =2A; V <sub>IN</sub> =0V; L=6mH	V <sub>CC</sub> -41	V <sub>CC</sub> -48	V <sub>CC</sub> -55	V
V <sub>ON</sub>	Output Voltage Drop Limitation	I <sub>OUT</sub> =1A; T <sub>J</sub> =-40°C....+150°C		50		mV

Note: 2. To ensure long term reliability under heavy overload or short circuit conditions, protection and related diagnostic signals must be used together with a proper software strategy. If the device is subjected to abnormal conditions, this software must limit the duration and number of activation cycles.

Table 10. Current Sense (9V≤V<sub>CC</sub>≤16V) (See Fig. 5)

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
K <sub>1</sub>	I <sub>OUT</sub> /I <sub>SENSE</sub>	I <sub>OUT</sub> =1A; V <sub>SENSE</sub> =0.5V; T <sub>J</sub> = -40°C...150°C	3300	4400	6000	
dK <sub>1</sub> /K <sub>1</sub>	Current Sense Ratio Drift	I <sub>OUT</sub> =1A; V <sub>SENSE</sub> =0.5V; T <sub>J</sub> = -40°C...+150°C	-10		+10	%
K <sub>2</sub>	I <sub>OUT</sub> /I <sub>SENSE</sub>	I <sub>OUT</sub> =10A; V <sub>SENSE</sub> =4V; T <sub>J</sub> =-40°C T <sub>J</sub> =25°C...150°C	4200 4400	4900 4900	6000 5750	
dK <sub>2</sub> /K <sub>2</sub>	Current Sense Ratio Drift	I <sub>OUT</sub> =10A; V <sub>SENSE</sub> =4V; T <sub>J</sub> =-40°C...+150°C	-8		+8	%
K <sub>3</sub>	I <sub>OUT</sub> /I <sub>SENSE</sub>	I <sub>OUT</sub> =30A; V <sub>SENSE</sub> =4V; T <sub>J</sub> =-40°C T <sub>J</sub> =25°C...150°C	4200 4400	4900 4900	5500 5250	
dK <sub>3</sub> /K <sub>3</sub>	Current Sense Ratio Drift	I <sub>OUT</sub> =30A; V <sub>SENSE</sub> =4V; T <sub>J</sub> =-40°C...+150°C	-6		+6	%
I <sub>SENSE0</sub>	Analog Sense Leakage Current	V <sub>CC</sub> =6...16V; I <sub>OUT</sub> =0A; V <sub>SENSE</sub> =0V; T <sub>J</sub> =-40°C...+150°C	0		10	μA
V <sub>SENSE</sub>	Max Analog Sense Output Voltage	V <sub>CC</sub> =5.5V; I <sub>OUT</sub> =5A; R <sub>SENSE</sub> =10KΩ V <sub>CC</sub> >8V; I <sub>OUT</sub> =10A; R <sub>SENSE</sub> =10KΩ	2 4			V V
V <sub>SENSEH</sub>	Sense Voltage in Overtemperature conditions	V <sub>CC</sub> =13V; R <sub>SENSE</sub> =3.9KΩ		5.5		V
R <sub>VSENSEH</sub>	Analog sense output impedance in overtemperature condition	V <sub>CC</sub> =13V; T <sub>J</sub> >T <sub>TSD</sub> ; Output Open		400		Ω
t <sub>DSENSE</sub>	Current sense delay response	to 90% I <sub>SENSE</sub> (see note 3)			500	μs

Note: 3. Current sense signal delay after positive input slope

Figure 5.  $I_{OUT}/I_{SENSE}$  versus  $I_{OUT}$

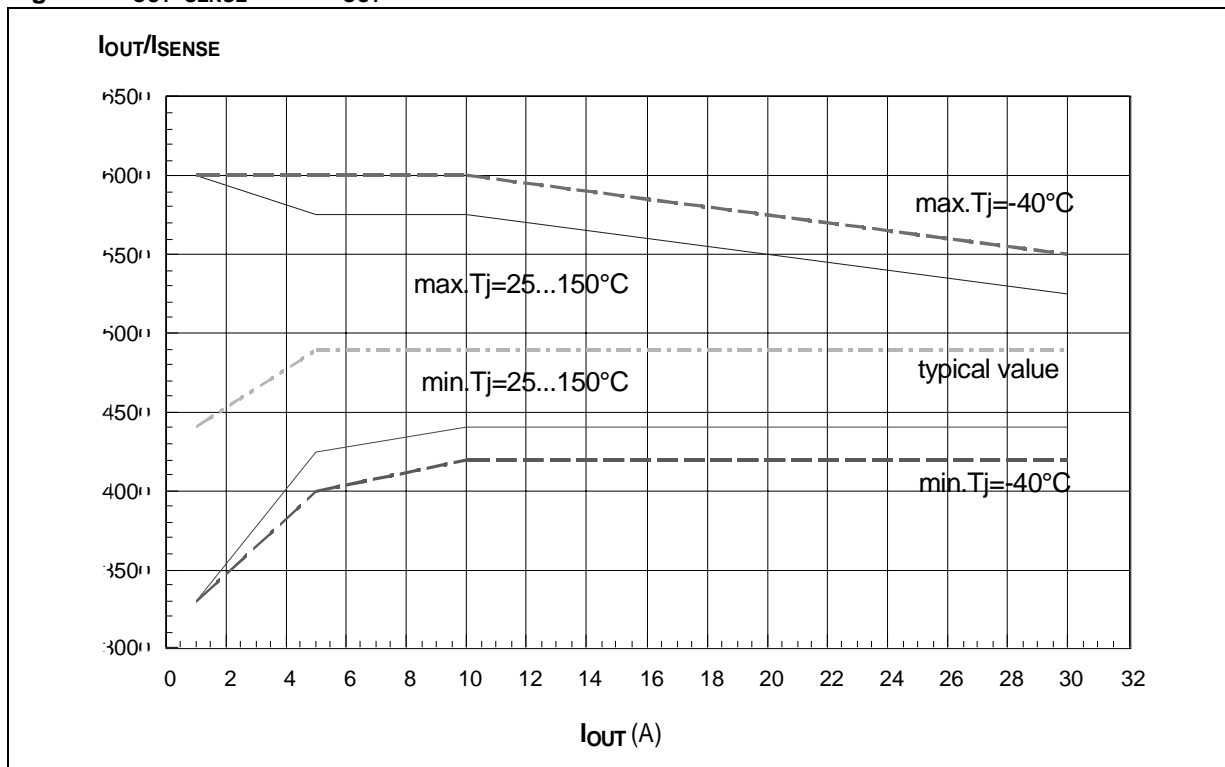


Figure 6. Switching Characteristics (Resistive load  $R_L = 1.3\Omega$ )

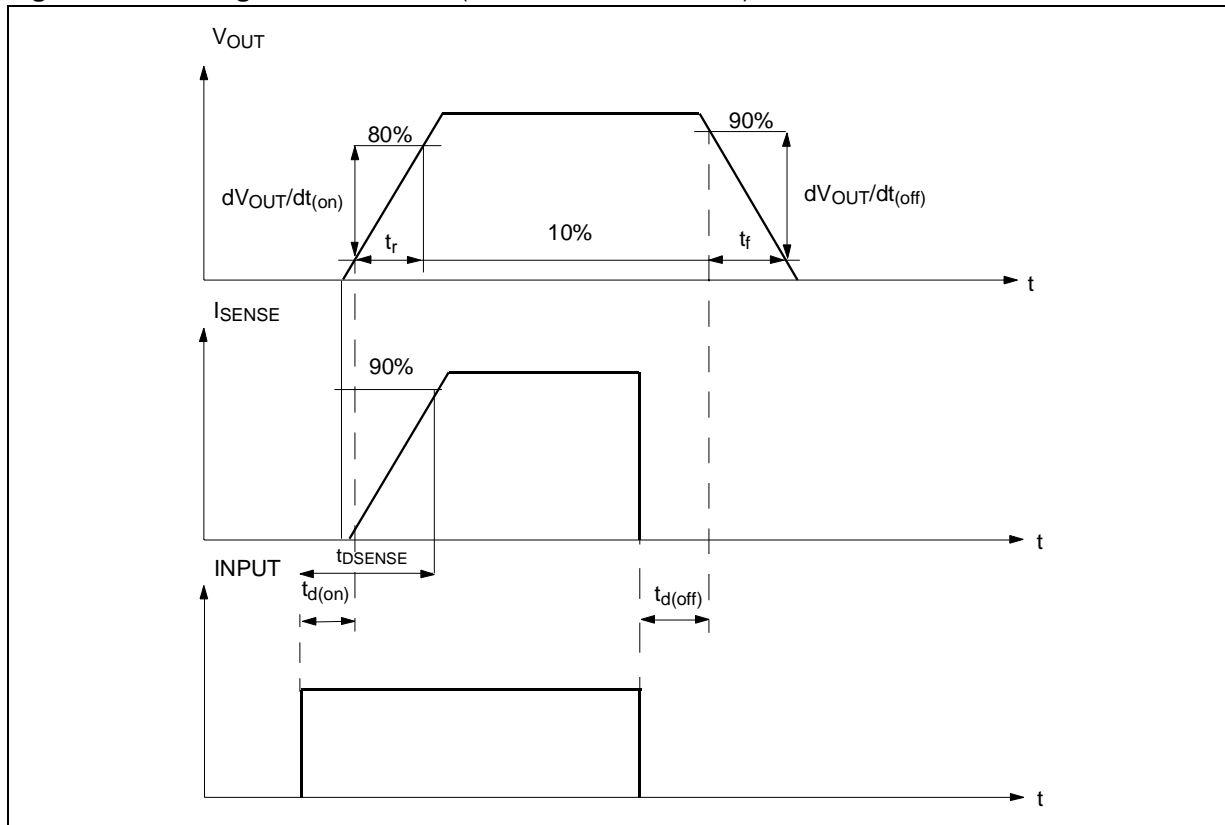


Table 11. Truth Table

CONDITIONS	INPUT	OUTPUT	SENSE
Normal operation	L	L	0
	H	H	Nominal
Overtemperature	L	L	0
	H	L	$V_{SENSEH}$
Undervoltage	L	L	0
	H	L	0
Overvoltage	L	L	0
	H	L	0
Short circuit to GND	L	L	0
	H	L	$(T_j < T_{TSD})$ 0
	H	L	$(T_j > T_{TSD})$ $V_{SENSEH}$
Short circuit to $V_{CC}$	L	H	0
	H	H	< Nominal
Negative output voltage clamp	L	L	0

Table 12. Electrical Transient Requirements On  $V_{CC}$  Pin

ISO T/R 7637/1 Test Pulse	TEST LEVELS				Delays and Impedance
	I	II	III	IV	
1	-25 V	-50 V	-75 V	-100 V	2 ms 10 $\Omega$
2	+25 V	+50 V	+75 V	+100 V	0.2 ms 10 $\Omega$
3a	-25 V	-50 V	-100 V	-150 V	0.1 $\mu$ s 50 $\Omega$
3b	+25 V	+50 V	+75 V	+100 V	0.1 $\mu$ s 50 $\Omega$
4	-4 V	-5 V	-6 V	-7 V	100 ms, 0.01 $\Omega$
5	+26.5 V	+46.5 V	+66.5 V	+86.5 V	400 ms, 2 $\Omega$

ISO T/R 7637/1 Test Pulse	TEST LEVELS RESULTS			
	I	II	III	IV
1	C	C	C	C
2	C	C	C	C
3a	C	C	C	C
3b	C	C	C	C
4	C	C	C	C
5	C	E	E	E

CLASS	CONTENTS
C	All functions of the device are performed as designed after exposure to disturbance.
E	One or more functions of the device is not performed as designed after exposure to disturbance and cannot be returned to proper operation without replacing the device.

Figure 7. Waveforms

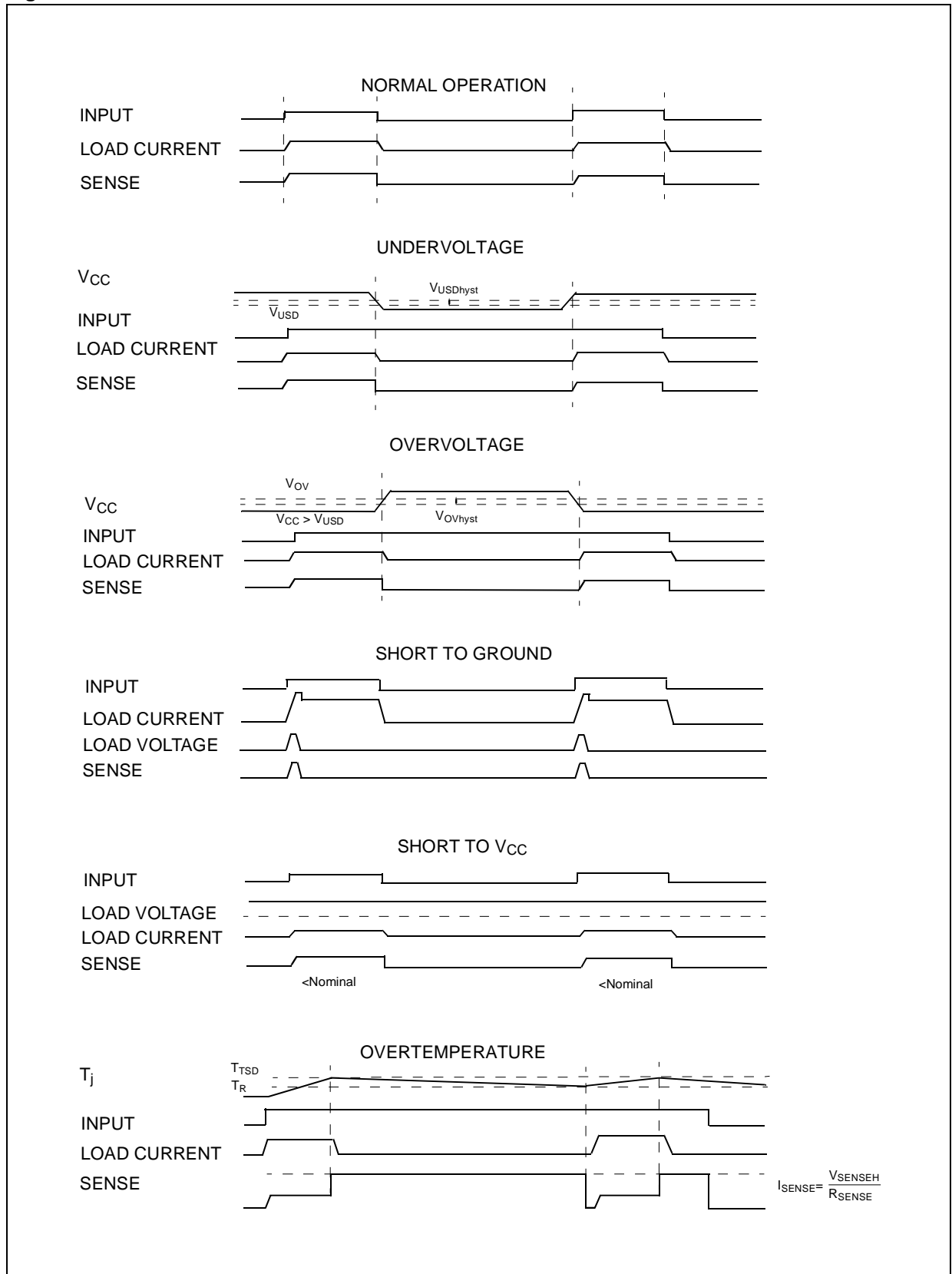
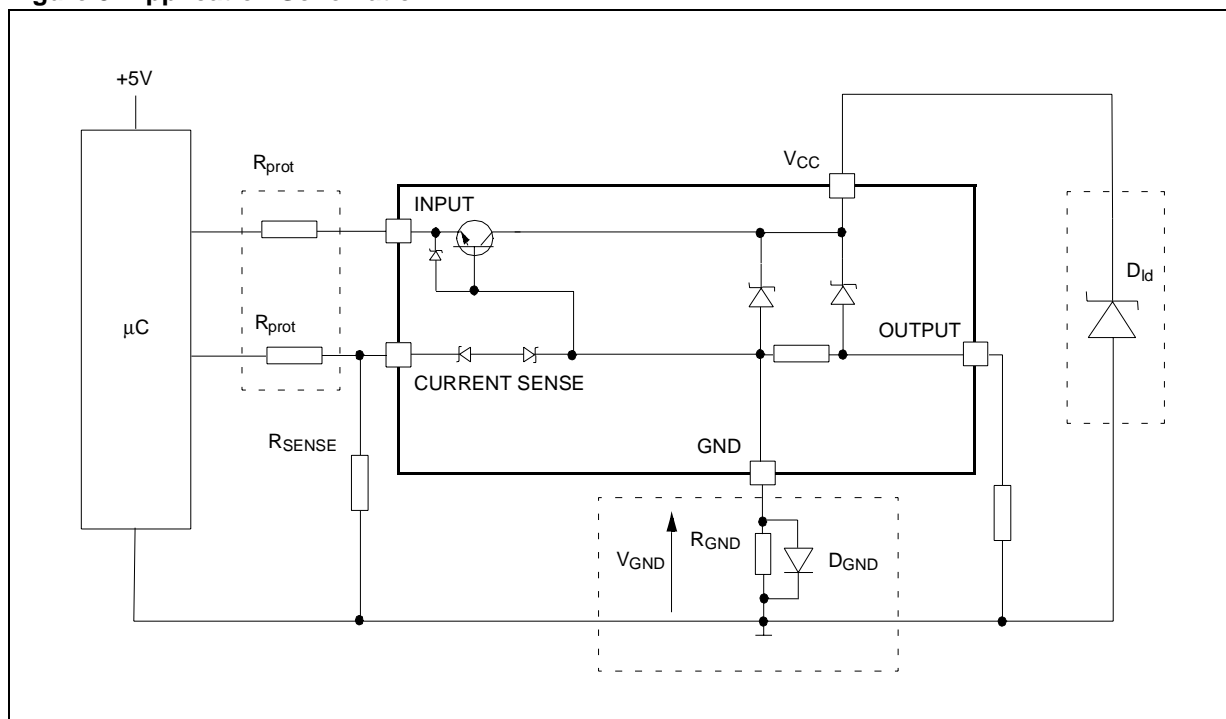




Figure 8. Application Schematic



### GND PROTECTION NETWORK AGAINST REVERSE BATTERY

**Solution 1:** Resistor in the ground line ( $R_{GND}$  only). This can be used with any type of load.

The following is an indication on how to dimension the  $R_{GND}$  resistor.

- 1)  $R_{GND} \leq 600\text{mV} / (I_{S(on)max})$ .
- 2)  $R_{GND} \geq (-V_{CC}) / (-I_{GND})$

where  $-I_{GND}$  is the DC reverse ground pin current and can be found in the absolute maximum rating section of the device's datasheet.

Power Dissipation in  $R_{GND}$  (when  $V_{CC} < 0$ : during reverse battery situations) is:

$$P_D = (-V_{CC})^2 / R_{GND}$$

This resistor can be shared amongst several different HSD. Please note that the value of this resistor should be calculated with formula (1) where  $I_{S(on)max}$  becomes the sum of the maximum on-state currents of the different devices.

Please note that if the microprocessor ground is not common with the device ground then the  $R_{GND}$  will produce a shift ( $I_{S(on)max} * R_{GND}$ ) in the input thresholds and the status output values. This shift will vary depending on how many devices are ON in the case of several high side drivers sharing the same  $R_{GND}$ .

If the calculated power dissipation leads to a large resistor or several devices have to share the same resistor then the ST suggests to utilize Solution 2 (see below).

**Solution 2:** A diode ( $D_{GND}$ ) in the ground line.

A resistor ( $R_{GND} = 1\text{k}\Omega$ ) should be inserted in parallel to  $D_{GND}$  if the device will be driving an inductive load.

This small signal diode can be safely shared amongst several different HSD. Also in this case, the presence of the ground network will produce a shift ( $\approx 600\text{mV}$ ) in the input threshold and the status output values if the microprocessor ground is not common with the device ground. This shift will not vary if more than one HSD shares the same diode/resistor network.

Series resistor in INPUT line is also required to prevent that, during battery voltage transient, the current exceeds the Absolute Maximum Rating.

Safest configuration for unused INPUT pin is to leave it unconnected, while unused SENSE pin has to be connected to Ground pin.

### LOAD DUMP PROTECTION

$D_{ID}$  is necessary (Voltage Transient Suppressor) if the load dump peak voltage exceeds  $V_{CC}$  max DC rating. The same applies if the device will be subject to transients on the  $V_{CC}$  line that are greater than the ones shown in the ISO T/R 7637/1 table.

### µC I/Os PROTECTION:

If a ground protection network is used and negative transients are present on the  $V_{CC}$  line, the control pins will be pulled negative. ST suggests to insert a resistor ( $R_{prot}$ ) in line to prevent the  $\mu\text{C}$  I/Os pins to latch-up.

The value of these resistors is a compromise between the leakage current of  $\mu\text{C}$  and the current required by the HSD I/Os (Input levels compatibility) with the latch-up limit of  $\mu\text{C}$  I/Os.

$$-V_{CCpeak} / I_{latchup} \leq R_{prot} \leq (V_{OH\mu C} - V_{IH} - V_{GND}) / I_{IHmax}$$

Calculation example:  
For  $V_{CCpeak} = -100\text{V}$  and  $I_{latchup} \geq 20\text{mA}$ ;  $V_{OH\mu C} \geq 4.5\text{V}$   
 $5\text{k}\Omega \leq R_{prot} \leq 65\text{k}\Omega$ .

Recommended  $R_{prot}$  value is  $10\text{k}\Omega$ .

Figure 9. Off State Output Current

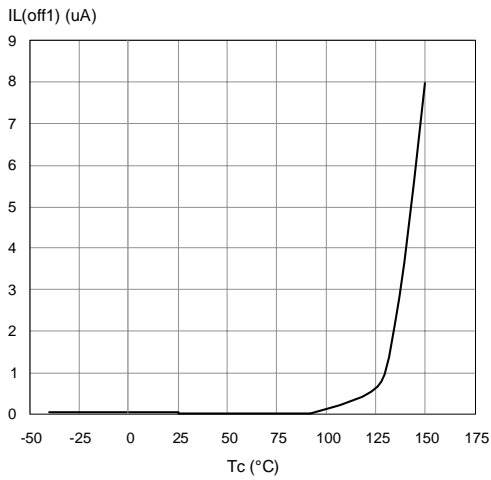


Figure 10. High Level Input Current

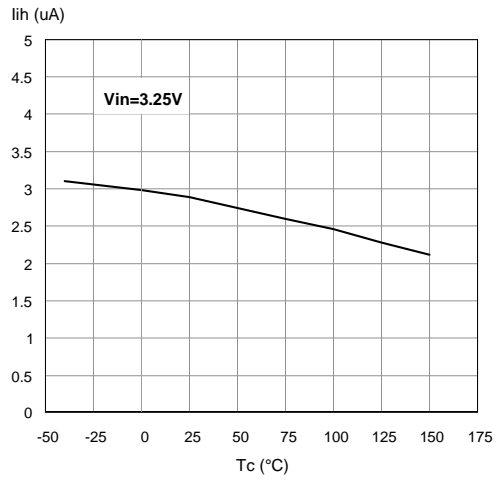


Figure 11. Input Clamp Voltage

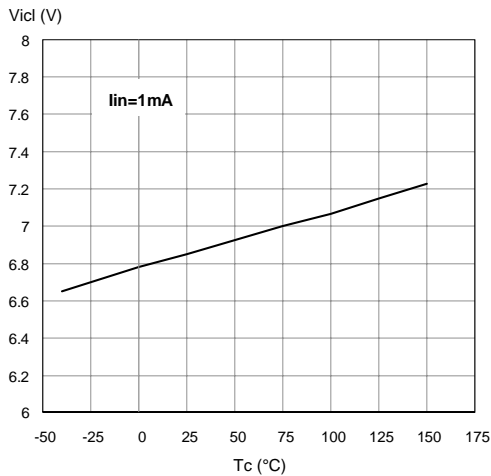


Figure 13. On State Resistance Vs VCC

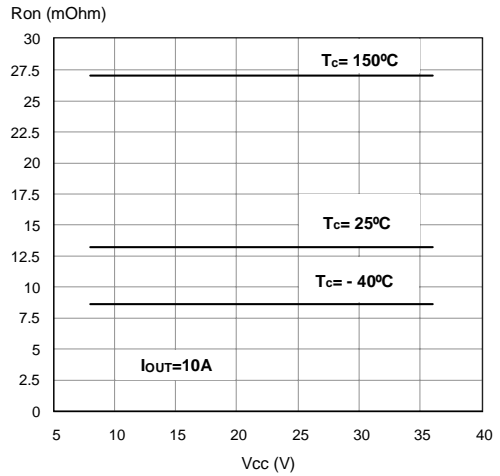


Figure 12. On State Resistance Vs Tcase

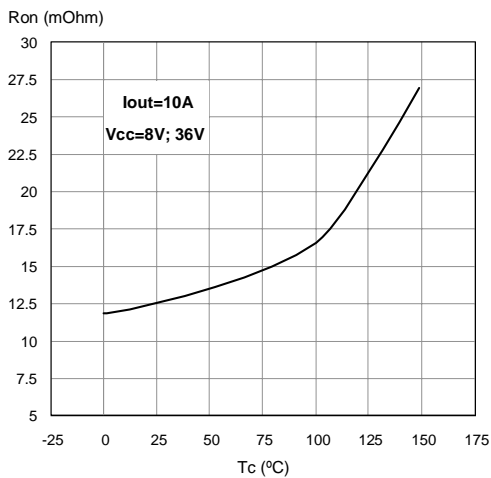


Figure 14. Input High Level

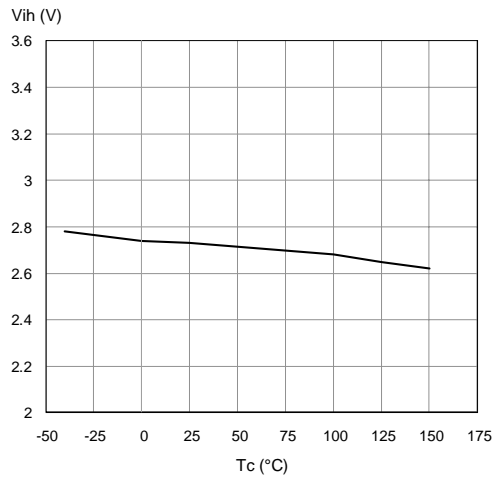


Figure 15. Input Low Level

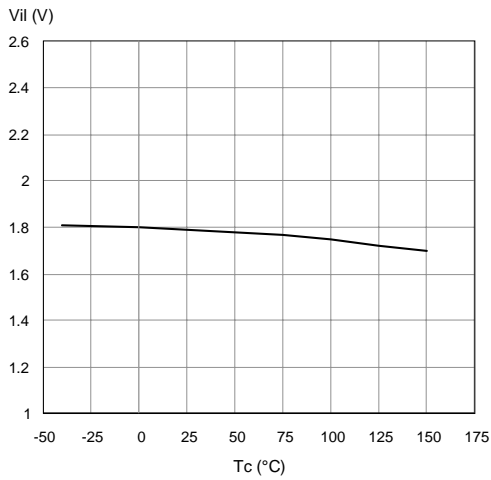


Figure 18. Input Hysteresis Voltage

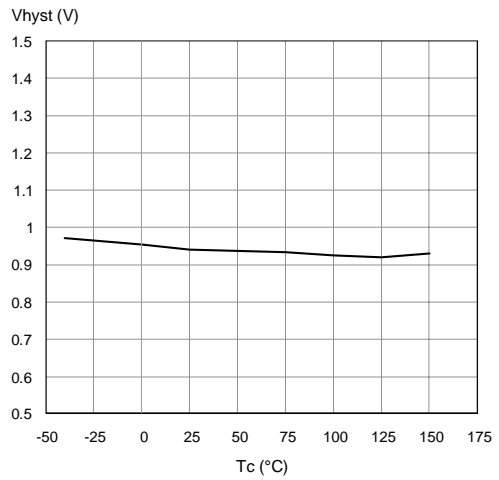


Figure 16. Turn-on Voltage Slope

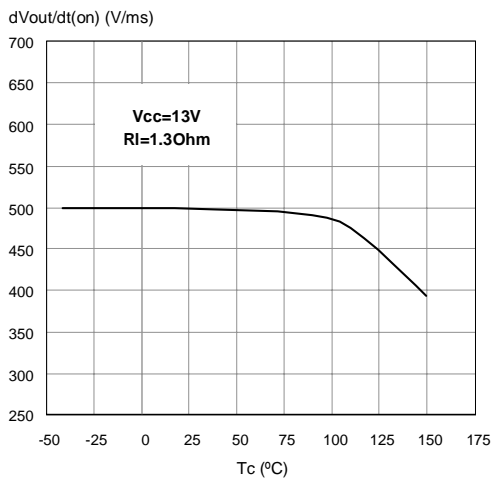


Figure 19. Turn-off Voltage Slope

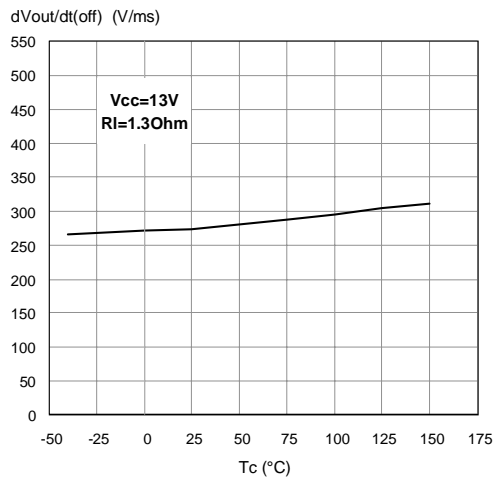


Figure 17. Overvoltage Shutdown

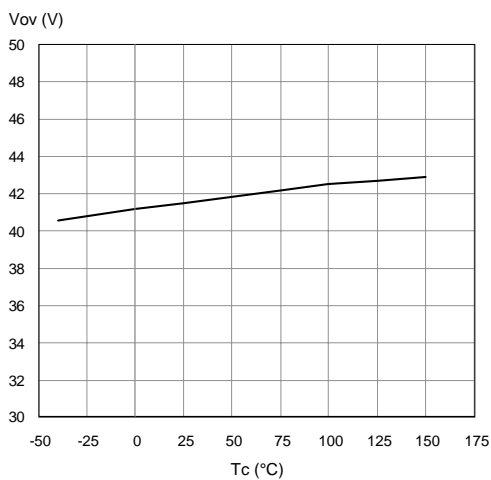


Figure 20. I<sub>LIM</sub> Vs T<sub>case</sub>

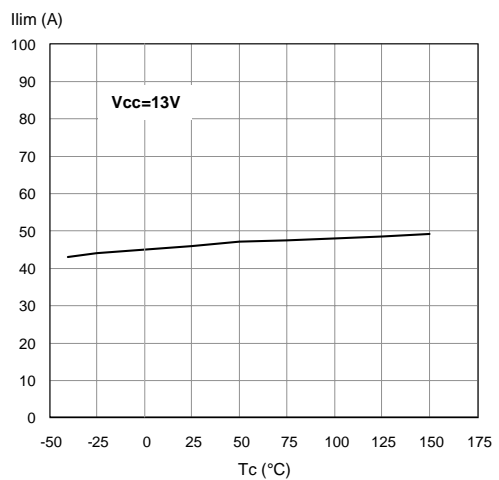
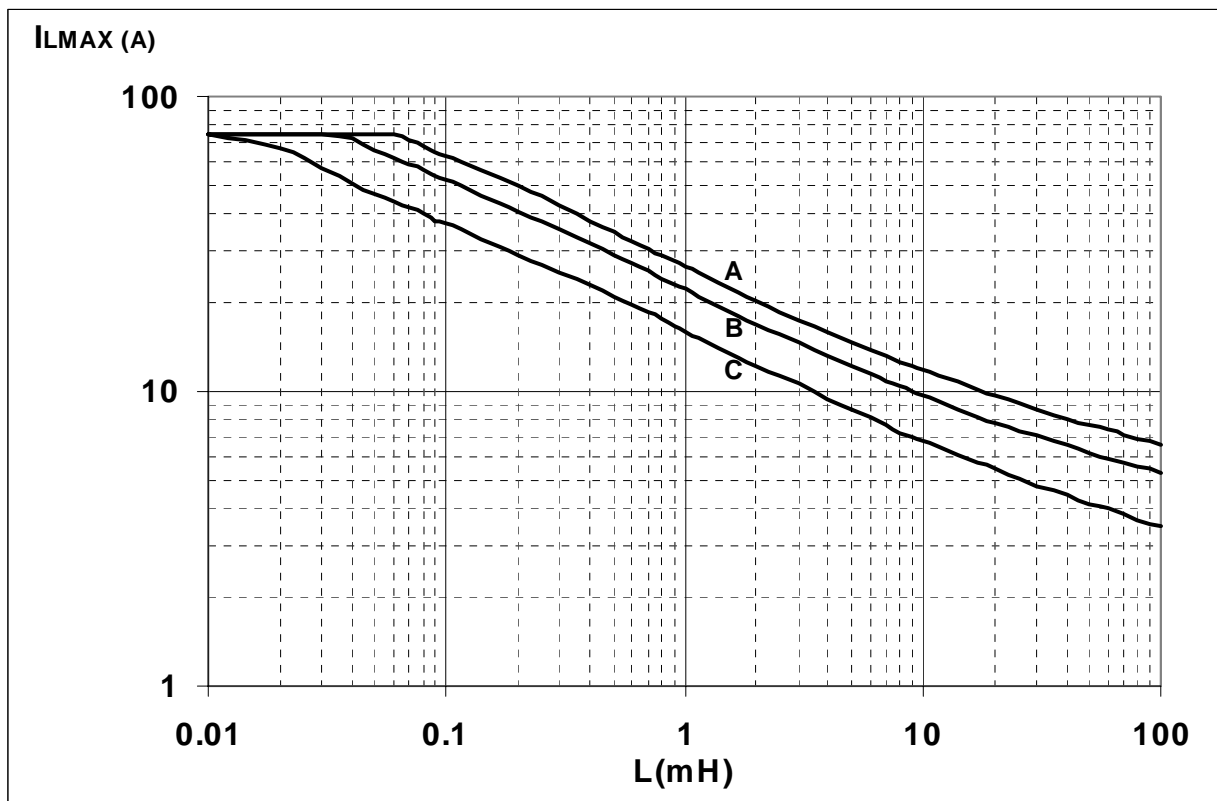


Figure 21. Maximum turn off current versus load inductance



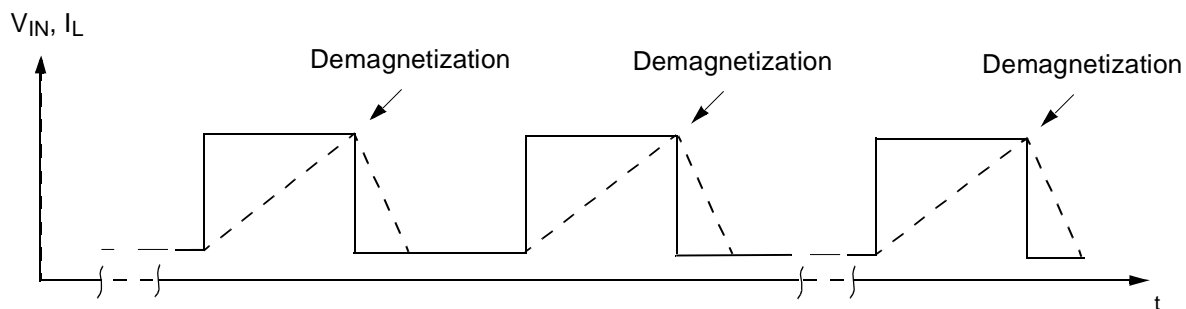
- A = Single Pulse at  $T_{Jstart}=150^{\circ}C$
- B = Repetitive pulse at  $T_{Jstart}=100^{\circ}C$
- C = Repetitive Pulse at  $T_{Jstart}=125^{\circ}C$

Values are generated with  $R_L=0\Omega$

In case of repetitive pulses,  $T_{Jstart}$  (at beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves B and C.

Conditions:

$V_{CC}=13.5V$



PowerSO-10™ Thermal Data

Figure 22. PowerSO-10™ PC Board

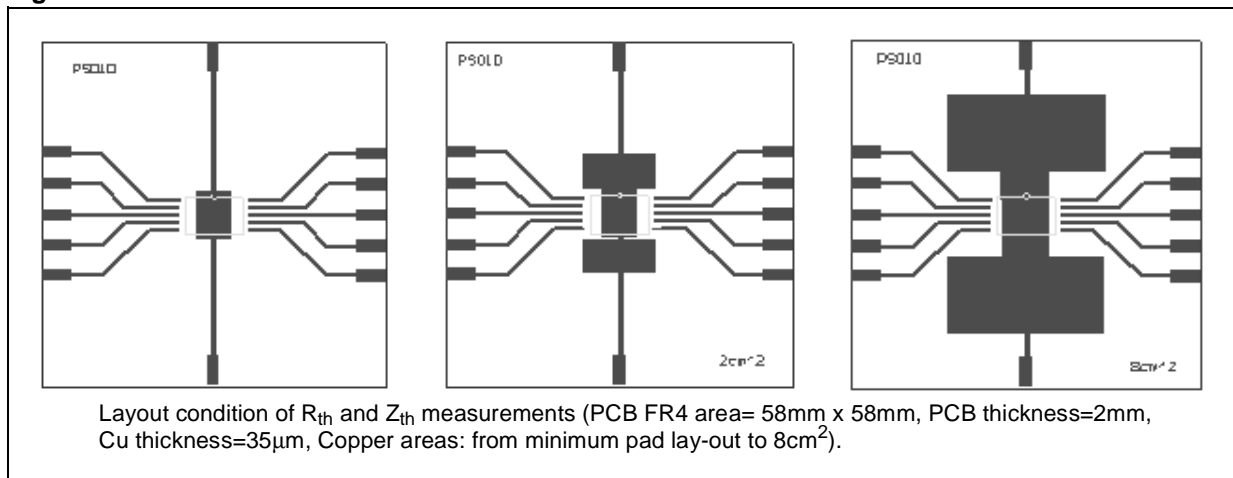


Figure 23.  $R_{thj-amb}$  Vs PCB copper area in open box free air condition

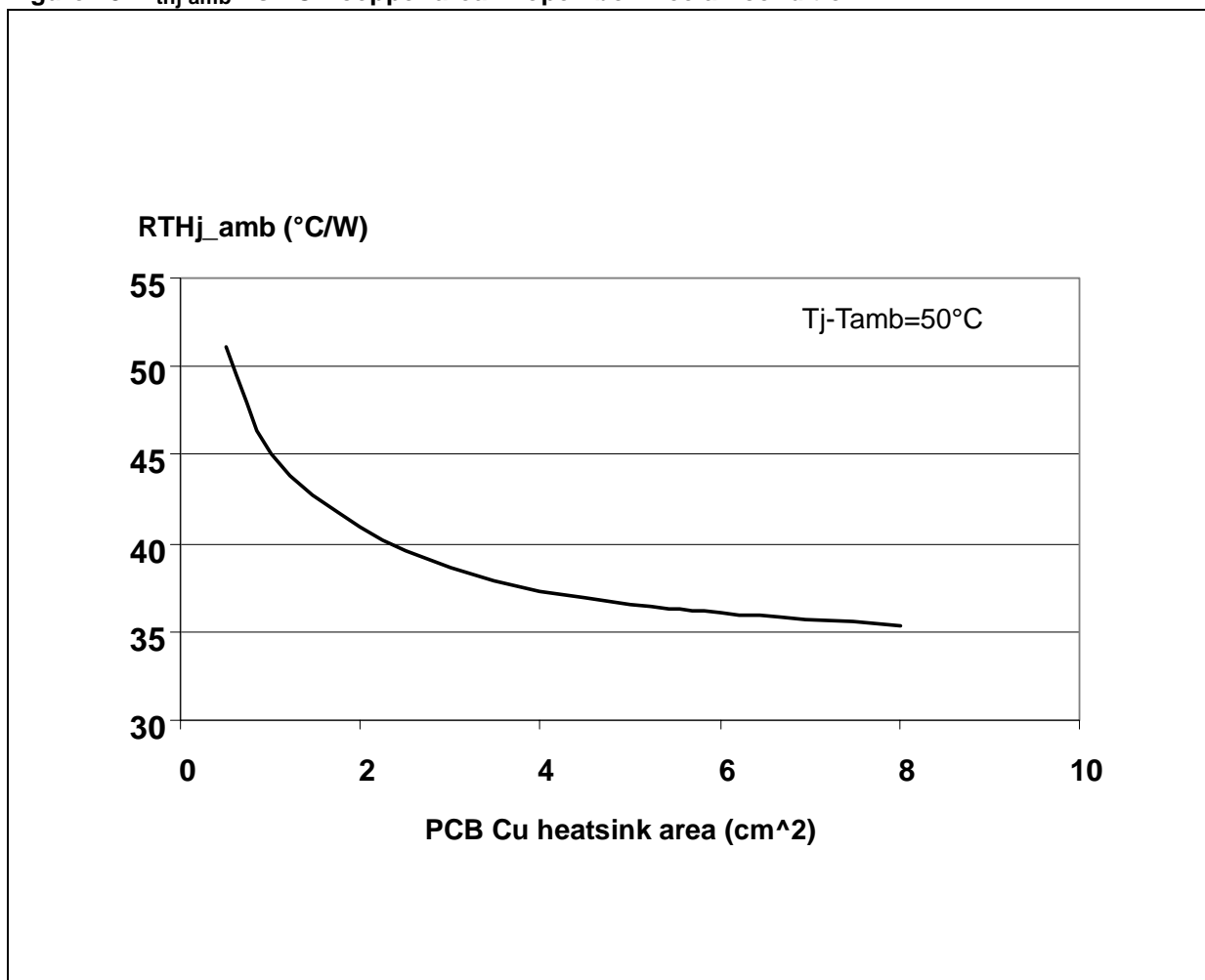


Figure 24. PowerSO-10 Thermal Impedance Junction Ambient Single Pulse

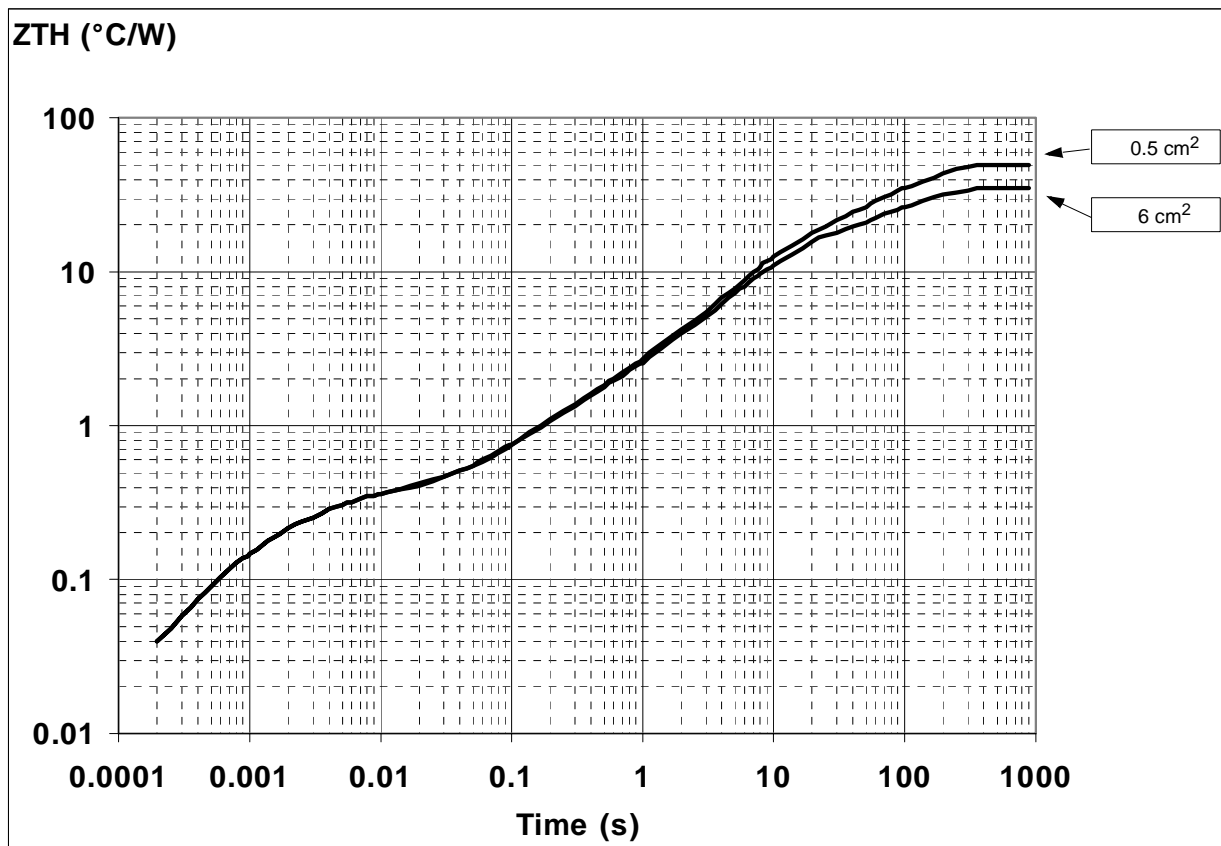
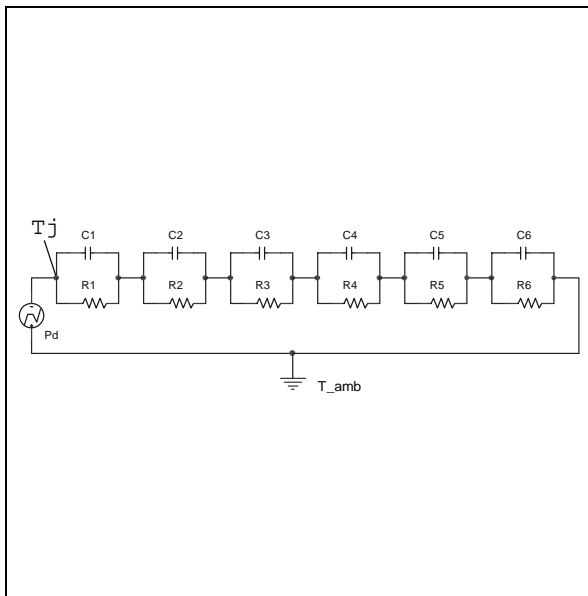


Figure 25. Thermal fitting model of a single channel HSD in PowerSO-10



Pulse calculation formula

$$T_{H\delta} = R_{TH} \cdot \delta + Z_{THtp}(1 - \delta)$$

where  $\delta = t_p/T$

Table 13. Thermal Parameter

Area/island (cm <sup>2</sup> )	Footprint	6
R1 (°C/W)	0.02	
R2 (°C/W)	0.1	
R3 (°C/W)	0.2	
R4 (°C/W)	0.8	
R5 (°C/W)	12	
R6 (°C/W)	37	22
C1 (W.s/°C)	0.0015	
C2 (W.s/°C)	7.00E-03	
C3 (W.s/°C)	0.015	
C4 (W.s/°C)	0.3	
C5 (W.s/°C)	0.75	
C6 (W.s/°C)	3	5

## PACKAGE MECHANICAL

Table 14. PowerSO-10™ Mechanical Data

Symbol	millimeters		
	Min	Typ	Max
A	3.35		3.65
A (*)	3.4		3.6
A1	0.00		0.10
B	0.40		0.60
B (*)	0.37		0.53
C	0.35		0.55
C (*)	0.23		0.32
D	9.40		9.60
D1	7.40		7.60
E	9.30		9.50
E2	7.20		7.60
E2 (*)	7.30		7.50
E4	5.90		6.10
E4 (*)	5.90		6.30
e		1.27	
F	1.25		1.35
F (*)	1.20		1.40
H	13.80		14.40
H (*)	13.85		14.35
h		0.50	
L	1.20		1.80
L (*)	0.80		1.10
a	0°		8°
α (*)	2°		8°

Note: (\*) Muar only POA P013P

Figure 26. PowerSO-10™ Package Dimensions

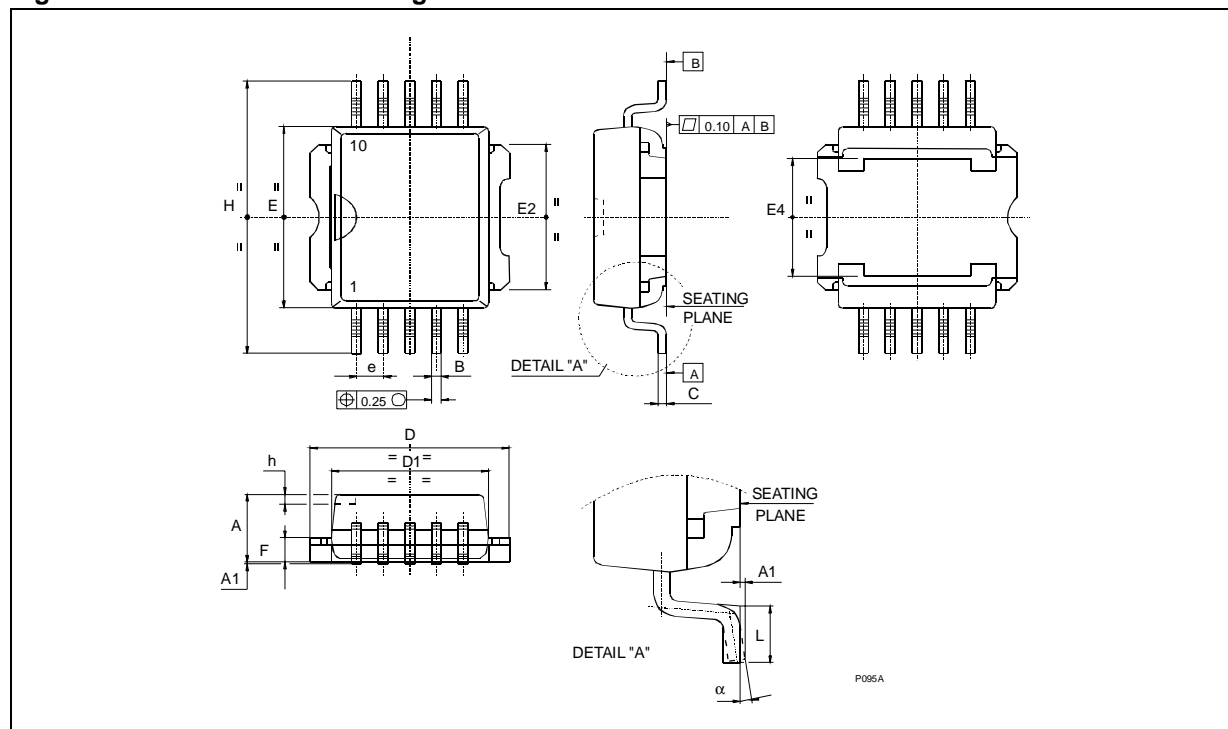


Figure 27. PowerSO-10™ Suggested Pad Layout And Tube Shipment (No Suffix)

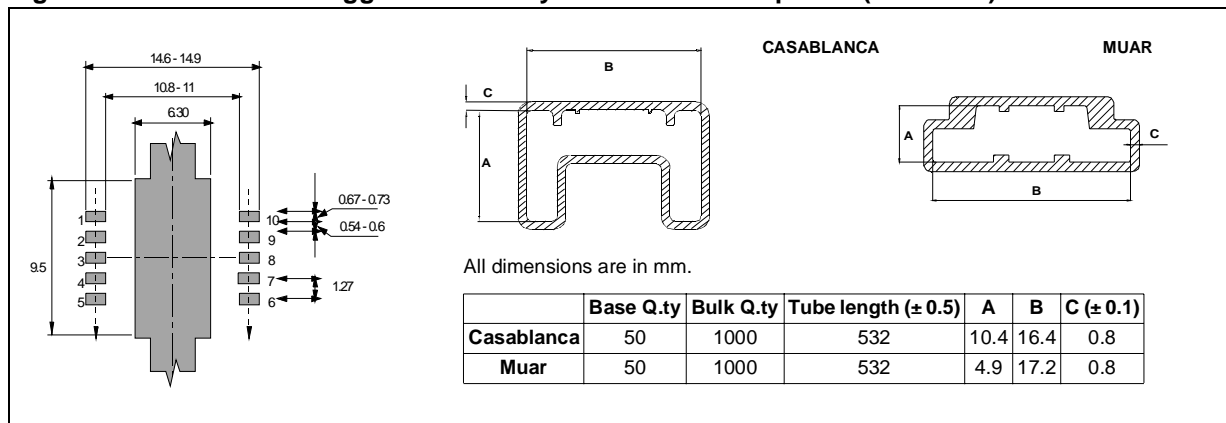
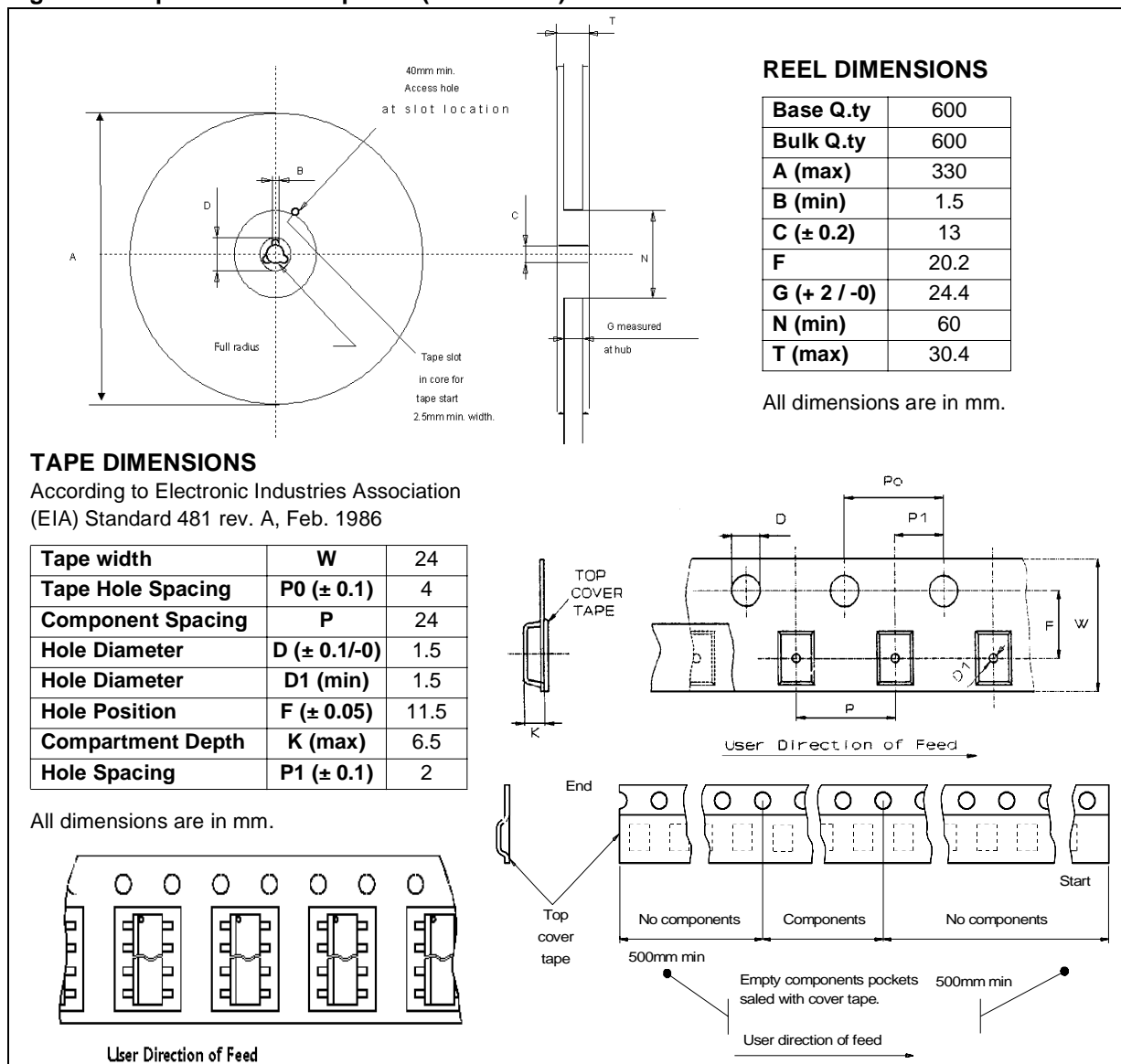


Figure 28. Tape And Reel Shipment (suffix “TR”)





---

**REVISION HISTORY****Table 15. Revision History**

Date	Revision	Description of Changes
Oct. 2004	1	- First Issue.

Information furnished is believed to be accurate and reliable. However, STMicroelectronics assumes no responsibility for the consequences of use of such information nor for any infringement of patents or other rights of third parties which may result from its use. No license is granted by implication or otherwise under any patent or patent rights of STMicroelectronics. Specifications mentioned in this publication are subject to change without notice. This publication supersedes and replaces all information previously supplied. STMicroelectronics products are not authorized for use as critical components in life support devices or systems without express written approval of STMicroelectronics.

The ST logo is a registered trademark of STMicroelectronics.  
All other names are the property of their respective owners

© 2004 STMicroelectronics - All rights reserved

STMicroelectronics group of companies

Australia - Belgium - Brazil - Canada - China - Czech Republic - Finland - France - Germany - Hong Kong - India - Israel - Italy - Japan -  
Malaysia - Malta - Morocco - Singapore - Spain - Sweden - Switzerland - United Kingdom - United States of America

[www.st.com](http://www.st.com)